**ADAPTIVE AND AUTONOMOUS AEROSPACE SYSTEMS**

P1L1: Useful introductory example and introduction to adaptive control  
P1L2: Useful for understanding the problem  
P1L3: Use just as a reference for nonlinear systems  
P1L4: Use just as a reference for stability definitions  
P1L5: Useful to revisit introductory example after revision of Lyapunov Stability (I will look for a reference for who is not familiar with Lyapunov’s theorems)  
P2L1 – P2L2 – P2L3: core slides, they provide an overview of all MRAC approach and analyze all critical aspects  
P2L4: Not essential at the moment  
P2L5: Same